

Learned simulators that satisfy the laws of Thermodynamics

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Deep Learning for Simulation (simDL)

We learn physics from data...

- When data refer to phenomena that conserve some quantities (typically, energy), it is easy to enforce this conservation.
- This can be done by enforcing the symplectic (Hamiltonian) structure of the dynamics:

$$\frac{dz}{dt} = \mathbf{L} \frac{\partial E}{\partial z},$$

with E the energy of the system and \mathbf{L} the symplectic (Poisson) matrix.

- But, how to proceed with dissipative phenomena?

... while enforcing the right thermodynamic structure

- This can be done by enforcing a metriplectic structure on the dynamics:

$$\frac{dz}{dt} = \mathbf{L} \frac{\partial E}{\partial z} + \mathbf{M} \frac{\partial S}{\partial z}.$$

- with \mathbf{L} skew-symmetric and \mathbf{M} symmetric, positive semi-definite.
- An additional constraint is necessary (*degeneracy conditions*):

$$\mathbf{L} \frac{\partial S}{\partial z} = \mathbf{M} \frac{\partial E}{\partial z} = \mathbf{0}.$$

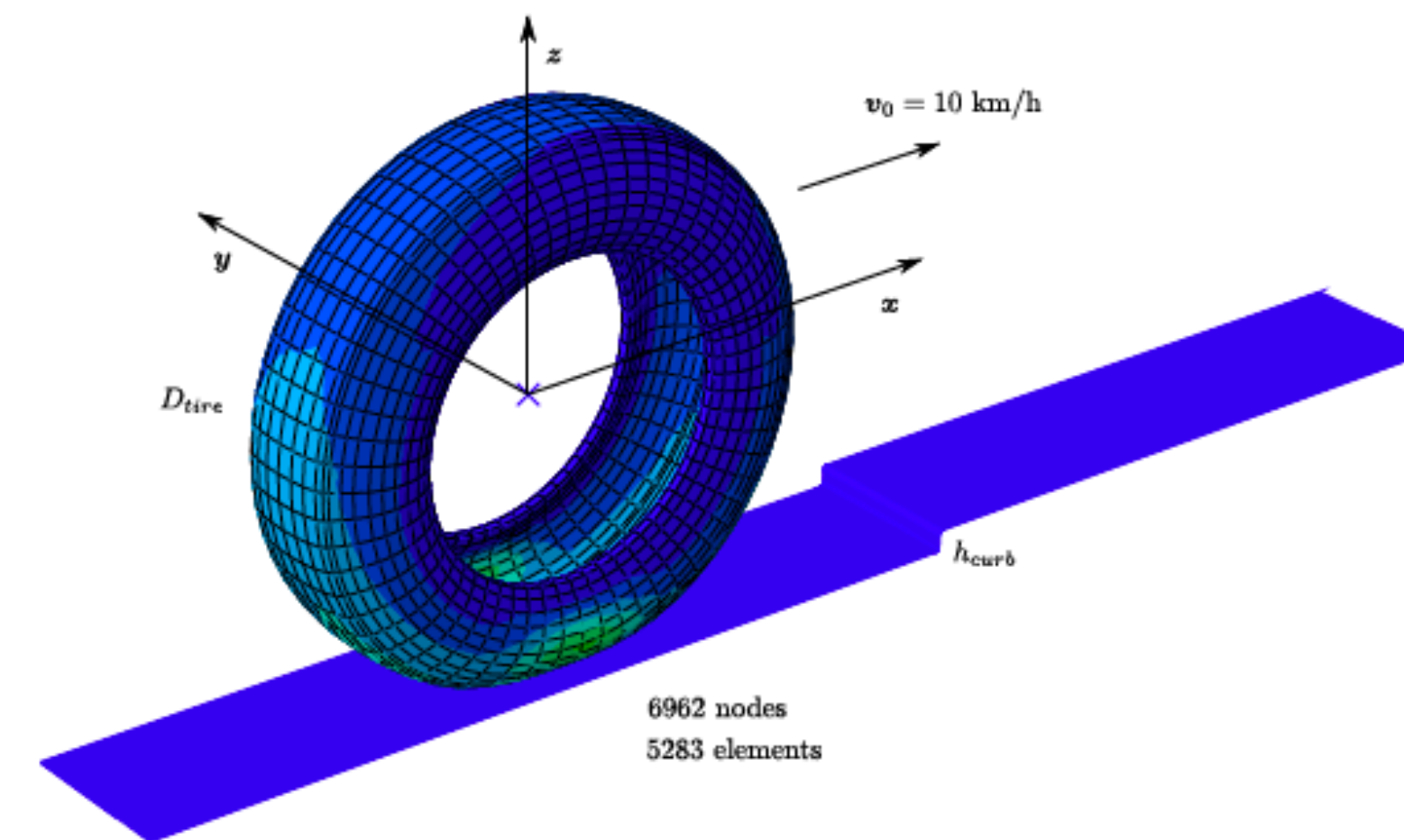
- This ensures the fulfillment of the first and second principles of thermodynamics.
- This is the so-called GENERIC formalism (Grmela and Oettinger, 1997).
- We augment the loss function with the fulfillment of the degeneracy conditions:

$$\mathcal{L}_n^{\text{degen}} = \|\mathbf{L}_n \cdot \mathbf{D}S_n\|_2^2 + \|\mathbf{M}_n \cdot \mathbf{D}E_n\|_2^2.$$

- Together with error and regularization terms, gives rise to

$$\mathcal{L}^{\text{SPNN}} = \frac{1}{N_{\text{train}}} \sum_{n=0}^{N_{\text{train}}} (\lambda_d^{\text{SPNN}} \mathcal{L}_n^{\text{data}} + \mathcal{L}_n^{\text{degen}}) + \lambda_r^{\text{SPNN}} \mathcal{L}^{\text{reg}}.$$

Example: tire facing a step

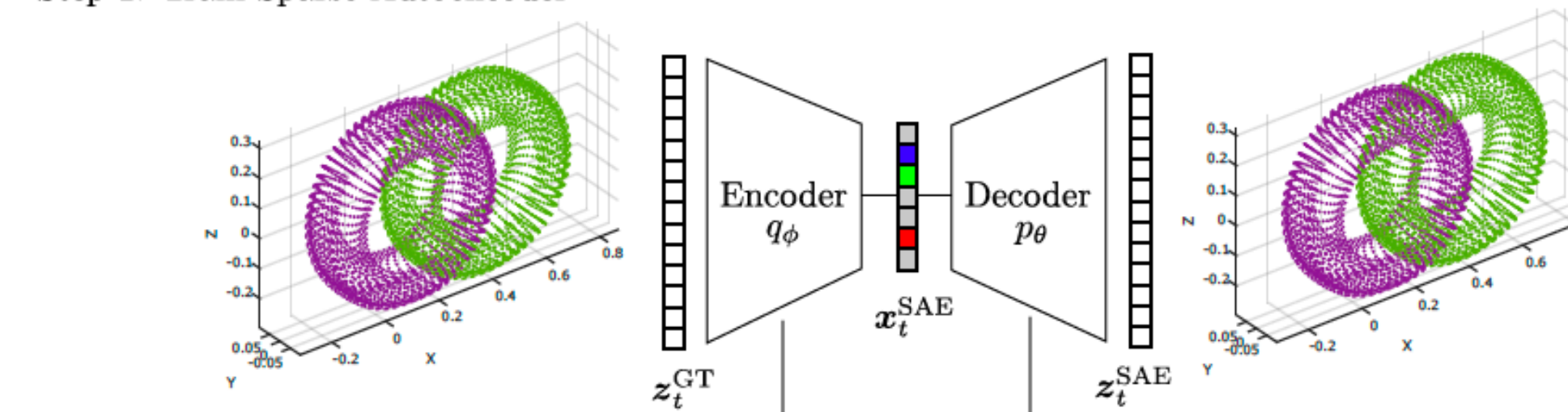


- As a proof-of-concept, we consider the problem of a non-linear, viscous-hyperelastic tire facing a step.
- Pseudo-data are taken from high-fidelity simulations.

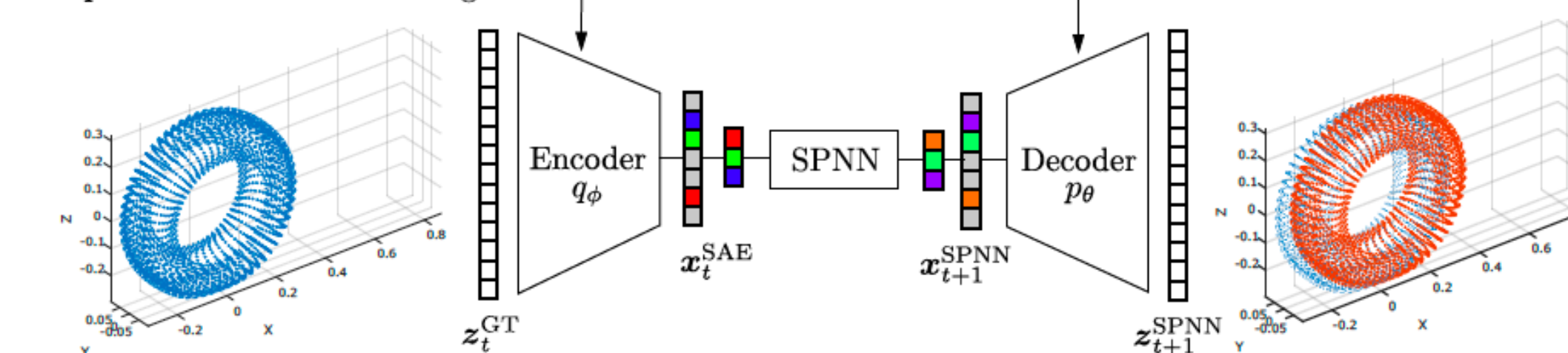
Architecture of the network

- We first unveil the intrinsic dimensionality of data with a sparse autoencoder (step 1).

Step 1: Train Sparse-Autoencoder



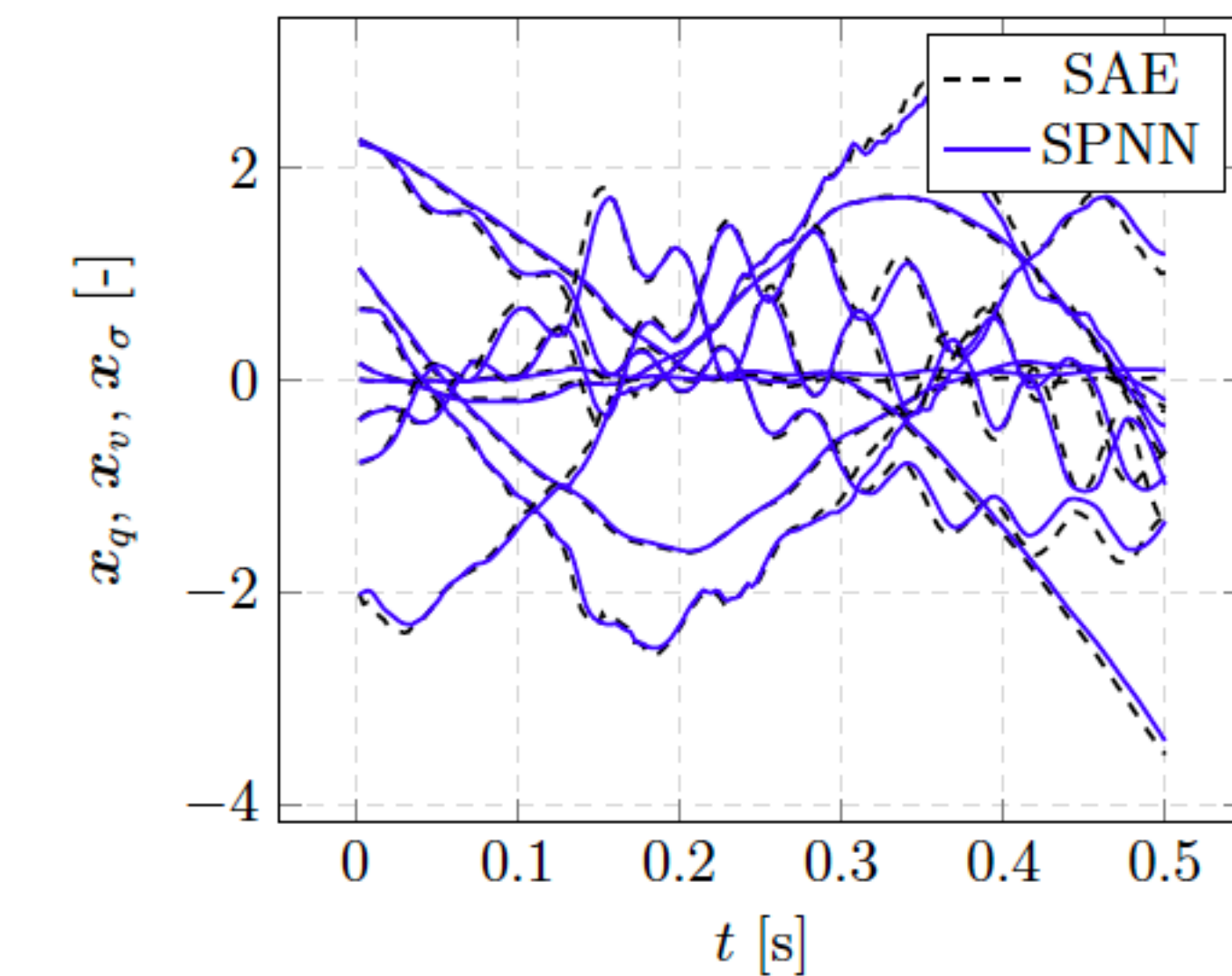
Step 2: Train GENERIC Integrator



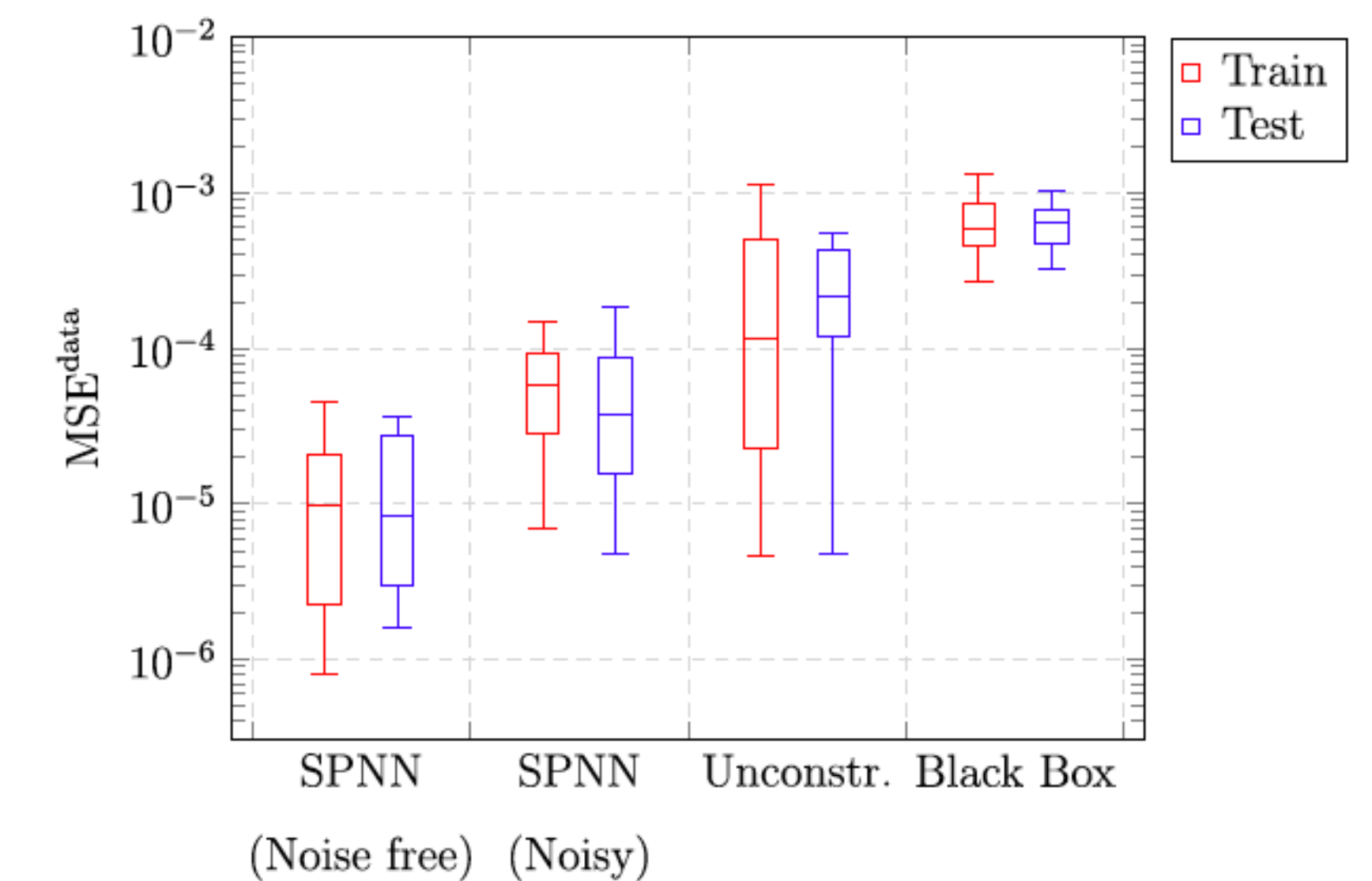
- We then learn a **structure-preserving neural network** (SPNN) on these low-dimensional data (step 2).
- This SPNN behaves as an energy-entropy-momentum integrator.
- Given the (low-dimensional) variables x at time t , it produces x at time $t+1$.

Results

- Error $\propto 10^{-4}$ with only 9 dofs, compared with the original 49680 dofs.



- The more physics you enforce, the more accurate results you obtain and the less data you will need:



References

Miroslav Grmela and Hans Christian Oettinger. Dynamics and thermodynamics of complex fluids. I. Development of a general formalism. In: *Physical Review E*, 56(6):6620, 1997.

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